

LAI and fAPAR validation under CEOS/LPV-VALERI

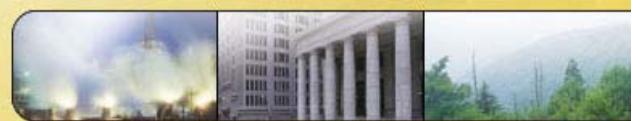
Landscape spatial patterns and the VALERI sampling strategy

The Shandan (CH) and Gilching (D) cases

Thursday, March 15th 2007

Frank Veroustraete

**Centre for Remote Sensing and Earth Observation (TAP)
Flemish Institute for Technological Research (VITO)**



*The **objectives** of the project:*

- To evaluate the **absolute accuracy** of bio- geophysical products (**LAI, fAPAR, fCover**) derived with a range of algorithms from **large IFOV sensors** (e.g. AVHRR, POLDER, VEGETATION, SEAWIFS, MSG, MERIS, AATSR, MODIS, MISR,...).
- To **inter-compare products** derived with different sensors and algorithms.

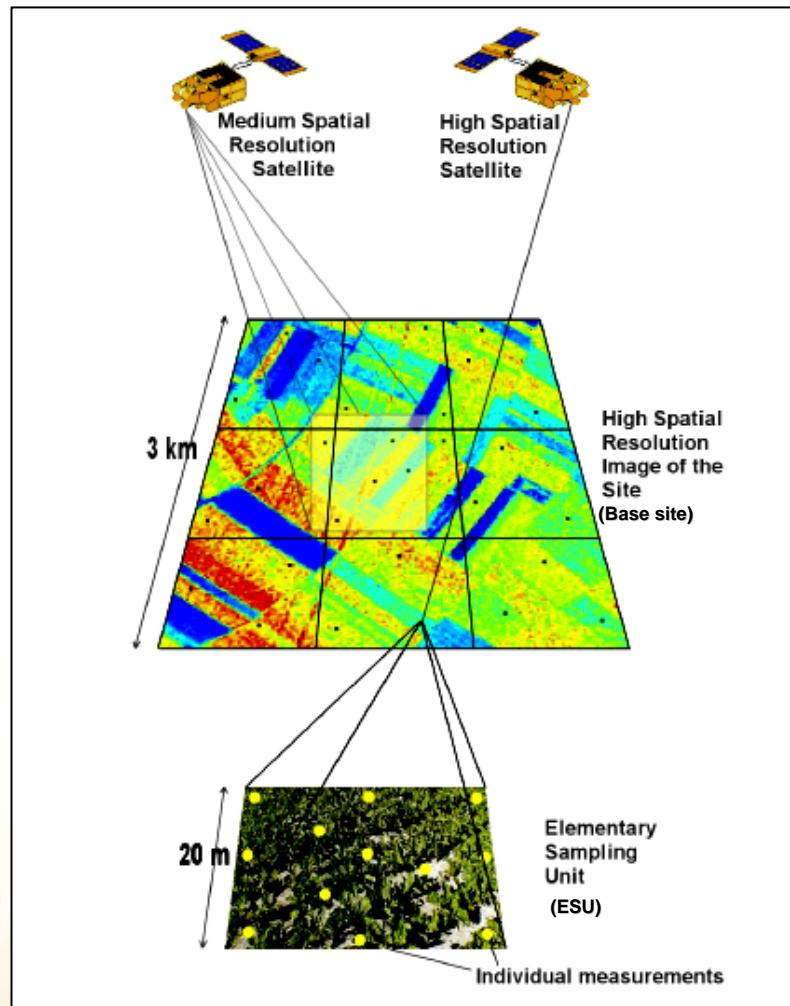
*For this purpose, the project **develops**:*

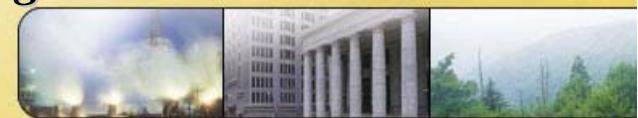
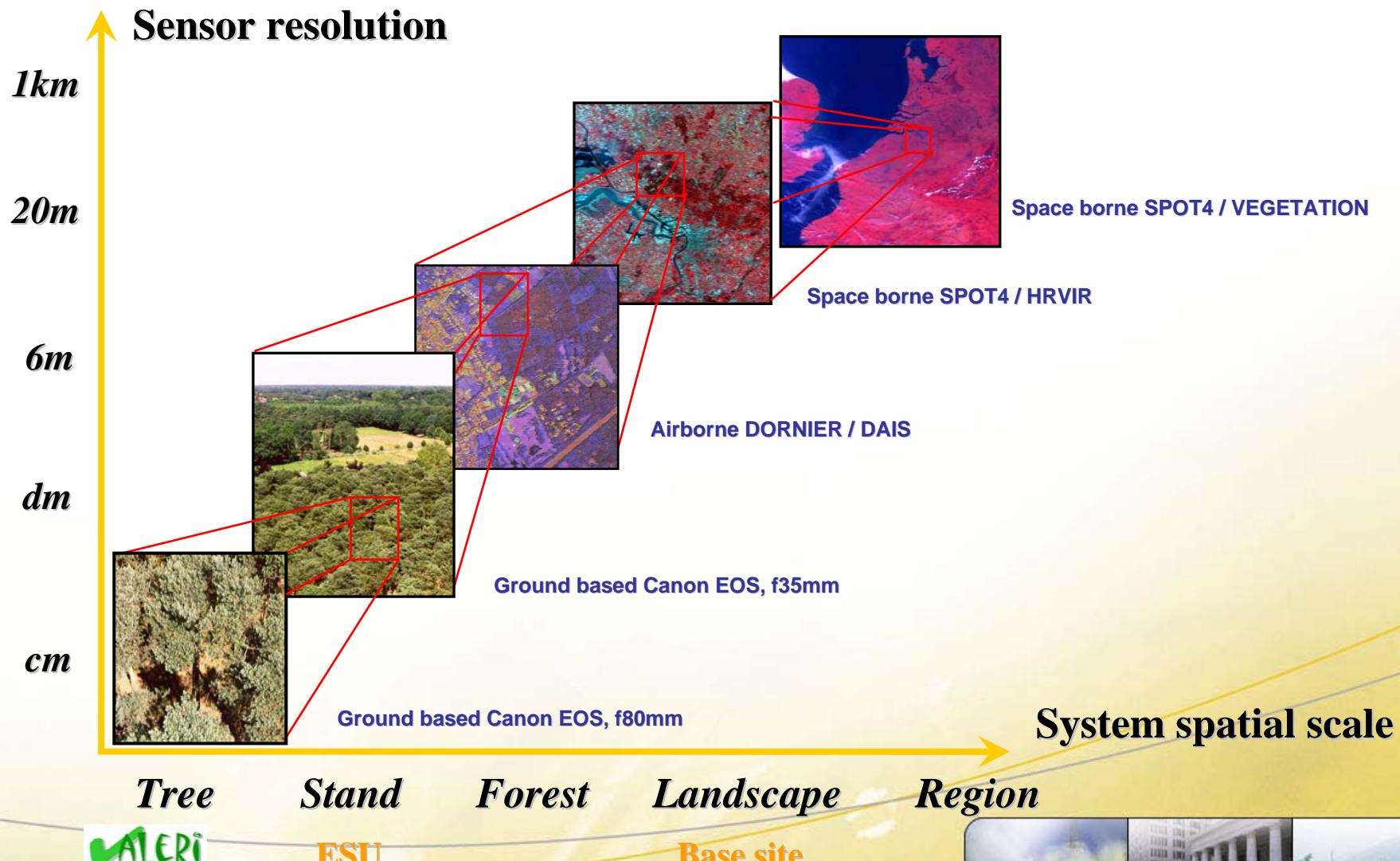
- A **network of sites** distributed globally.
- A **standard methodology** designed to directly measure the bio-geophysical variables of interest at the proper **spatial and temporal scales**.



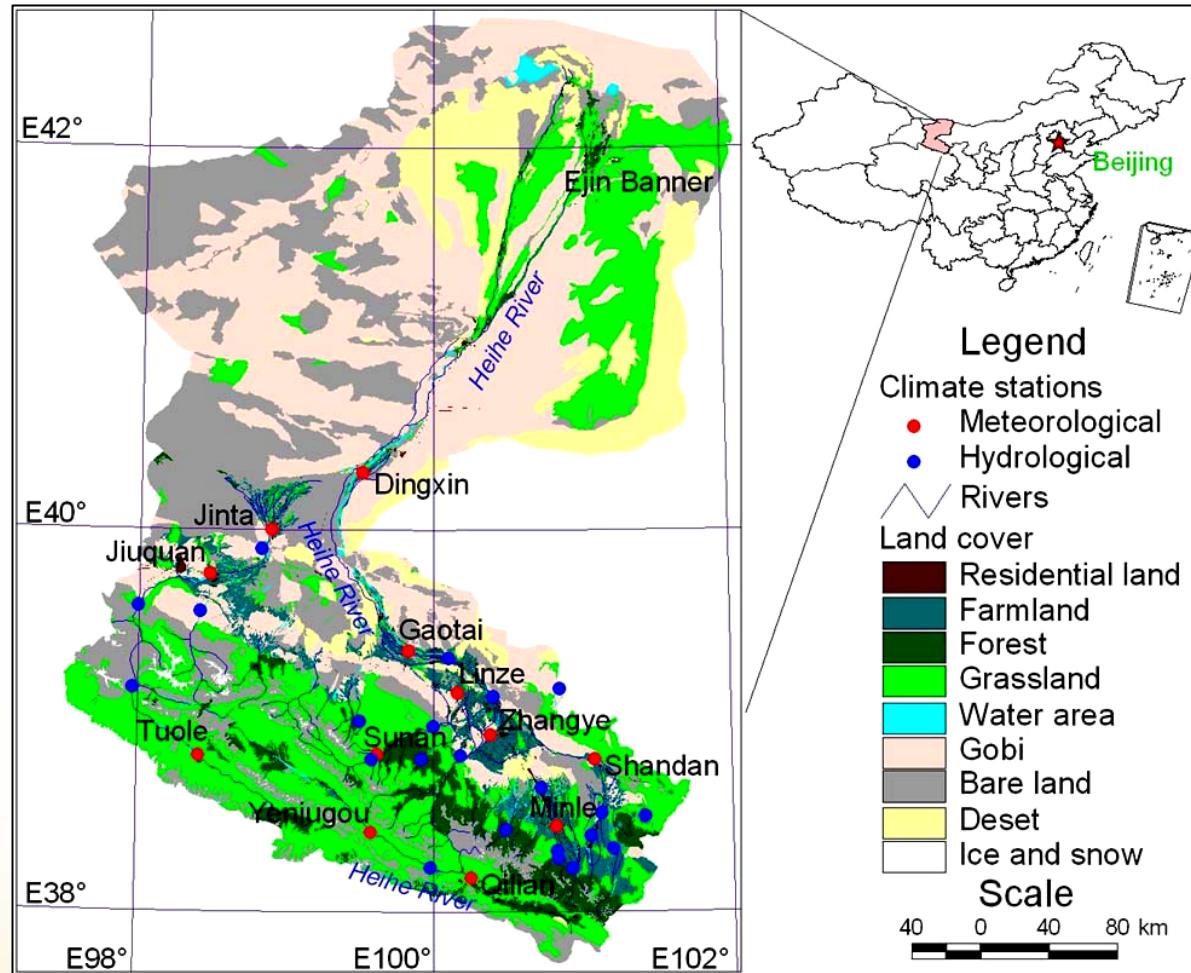


Up-scaling strategy

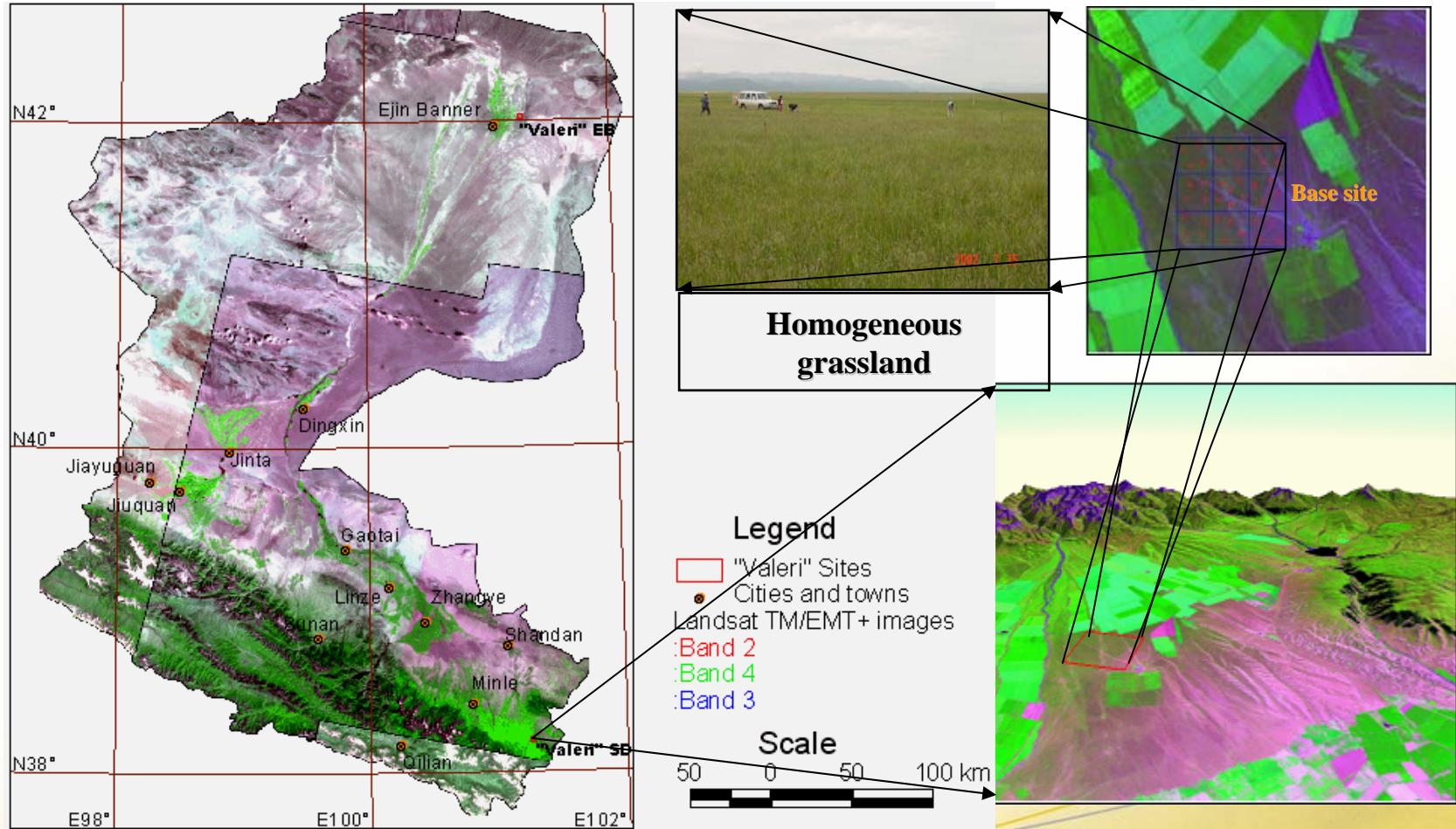




The VALERI Shandan site (Gansu province, CH)

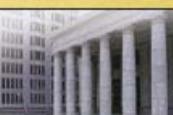
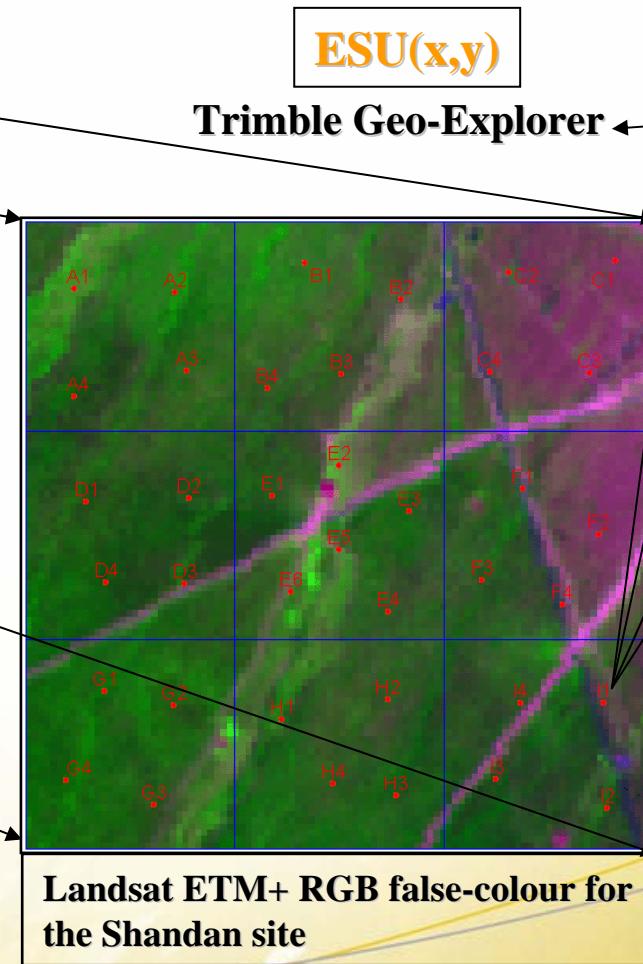
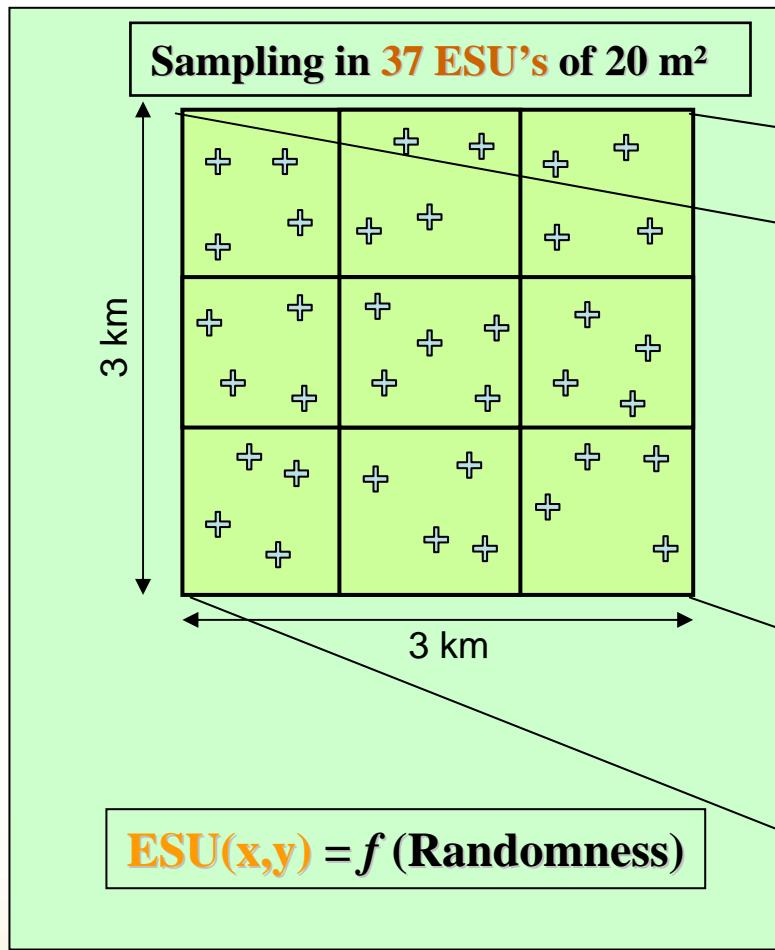


The Shandan site





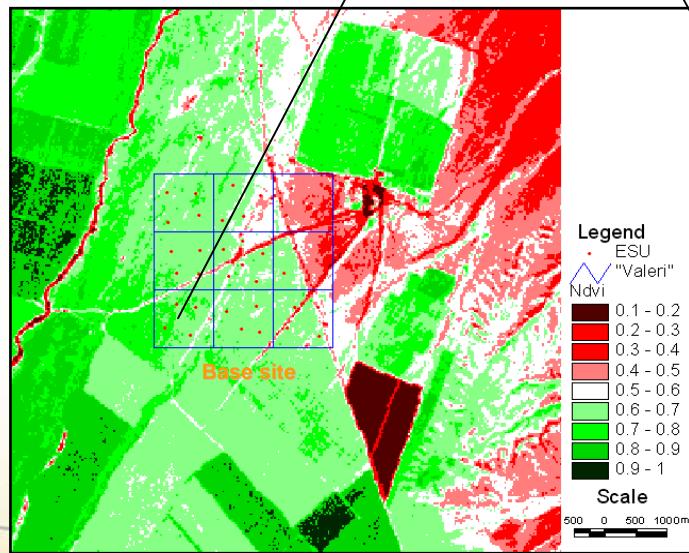
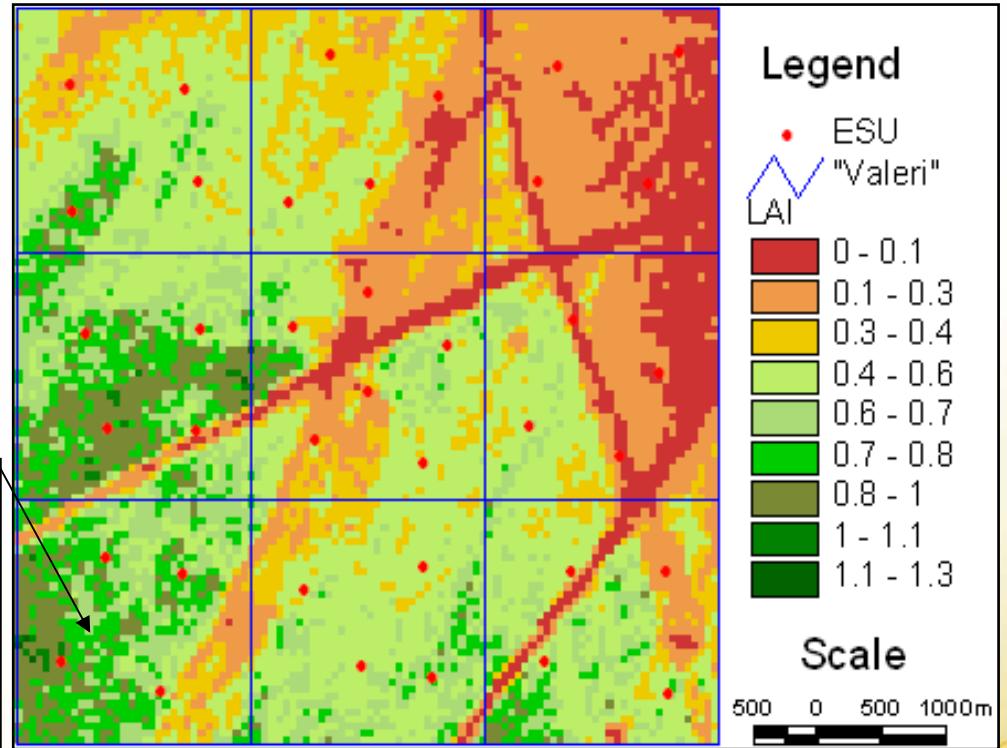
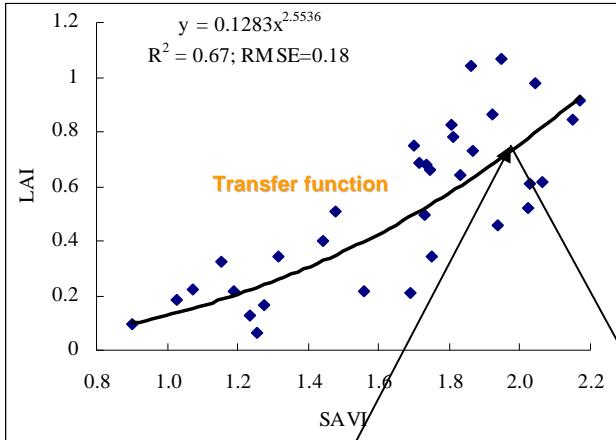
VALERI spatial sampling strategy in a homogeneous landscape



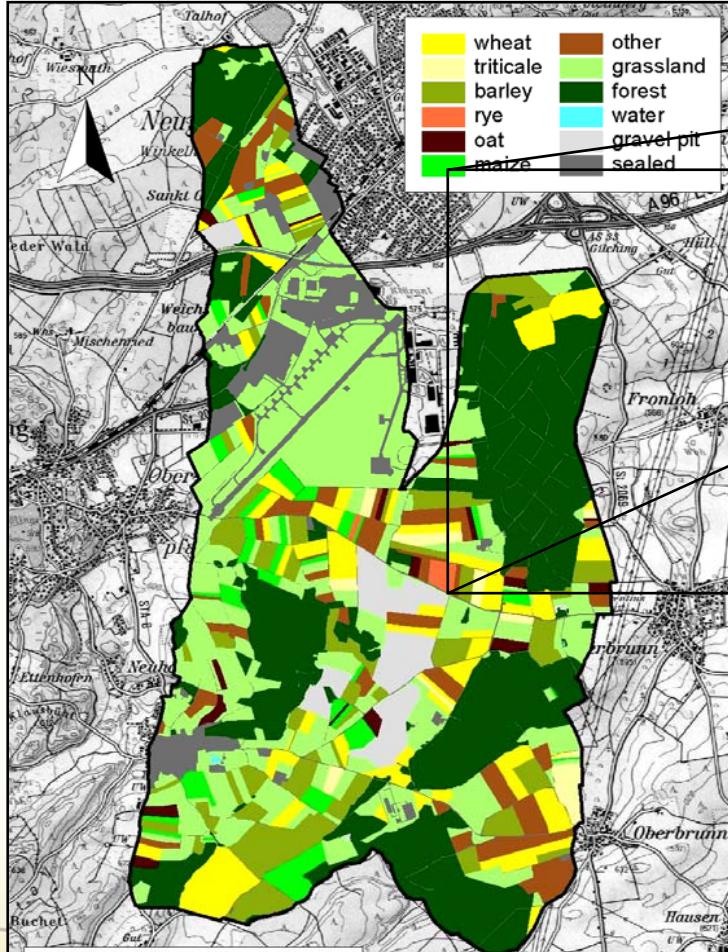
- Each 3 km² base site contains a number of randomly positioned and rotated 20 m² ESU's.
- The angle of ESU line FB with the true North is chosen randomly.
- Each 1 km² pixel in the base site has 4 ESU's. The central pixel has 5 ESU's.
- In each 20 m² ESU, discrete bio- geophysical variables measurements take place at nine points (A, B, C, D, E, F, G, H, O).
- In each 20 m² ESU continuous biophysical variables measurements take place along eight lines (AC, CE, EG, GA, AE, CG, BF, HD), or according to the sun's position.
- The ESU centre point (O) is determined with a Trimble Geo-explorer 2 GPS. All other ESU measuring points co-ordinates are thereby determined.
- Only one single transfer function for the whole base site is required.



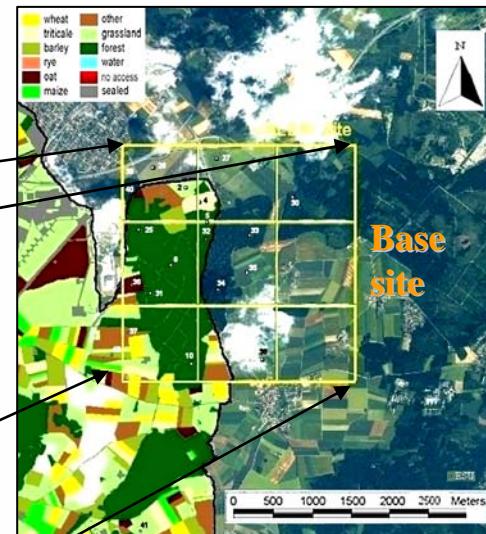
VALERI Example of LAI up-scaling with ETM+ SAVI



The VALERI Gilching site (Bavaria, D)



3 km

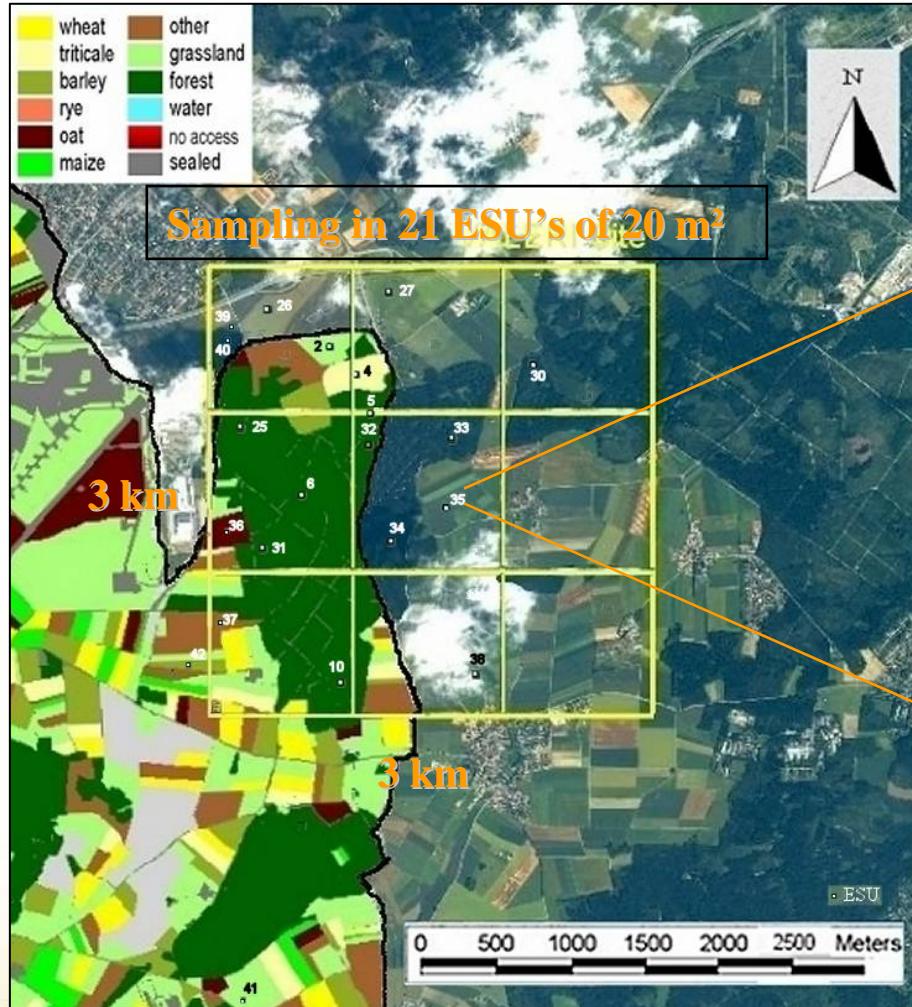


3 km

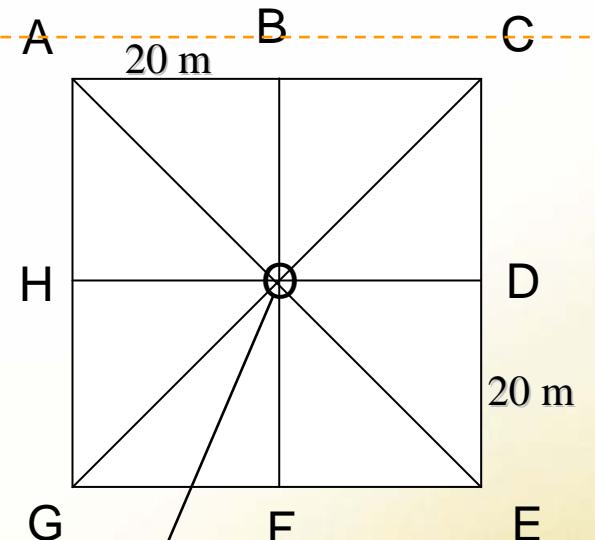
'European' patchy landscape



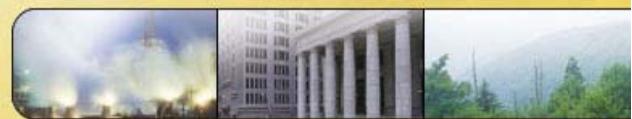
The VALERI Gilching site (Bavaria)



$$ESU(x,y) = f(\text{landcover})$$



Trimble GeoExplorer → $ESU(x,y)$



- Each 3 km² base site contains a number of 20 m² ESU's positioned according to landcover type.
- The angle of ESU line FB with the true North is chosen randomly.
- Each 1 km² pixel in the base site has a number of ESU's according to the number of different landcover type patches.
- In each 20 m² ESU, discrete biophysical variables measurements take place at nine points (A, B, C, D, E, F, G, H, O).
- In each 20 m² ESU continuous biophysical variables measurements take place along eight lines (AC, CE, EG, GA, AE, CG, BF, HD), or according to the sun's position.
- The ESU centre point (O) is determined with a Trimble Geo-explorer 2 GPS. All other ESU measuring points co-ordinates are thereby determined.
- As many transfer functions as land cover types for the base site.



➤ ***Indirect methods***

✓ ***Tracing radiation and Architecture of Canopies (TRAC – CCRS)***

- ✓ Gap size distribution, fAPAR, clumping index, effective LAI
- ✓ Continuous measurement in 20 m block (steady pace walks).
- ✓ Dedicated software package from CCRS.
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed.

✓ ***Hemispherical photography (HDP) (Nikon Coolpix 5000 and fish-eye)***

- ✓ Effective and ‘true LAI’, fAPAR, fCover, clump size index, canopy architecture
- ✓ Software: INRA Avignon software package CANEYE
- ✓ Discrete measurements on 20 m ESU points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed

✓ ***Licor LAI-2000***

- ✓ Measurement of effective LAI
- ✓ Discrete measurements on 20 m block points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Interesting comparisons possible with HDP and TRAC (I. Jonckheere, FEM, 2006)



indirect method (TRAC)

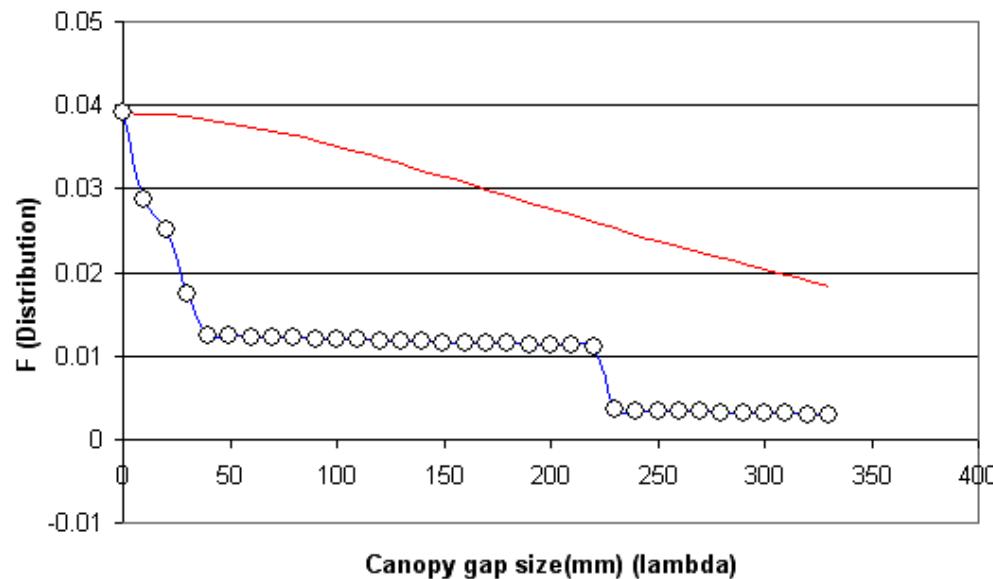
Fm: Non-random canopies like in plantations and natural forests (measured gap size distribution)

Fmr: Gap size distribution after excessive gaps have been removed iterated till a portion of Fmr falls below Fr

Fr: Random case and final solution of F. Assumes canopy with negligible woody material excessive gaps removed and random foliage distribution.

Beech

ESU06 TRAC F Plot (Gap size distribution)



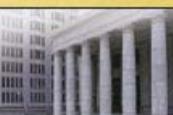
Mean Solar Zenith Angle in the transect = 36.4

PAle= 5.2 LAI = 4.4

For LAI calculation gaps are removed, so based on Fr distribution.

Ω from data: 53.9 mm

Ω : Foliage typical width



➤ ***Indirect methods***

✓ ***Tracing radiation and Architecture of Canopies (TRAC – CCRS)***

- ✓ Gap size distribution, fAPAR, clumping index, effective LAI
- ✓ Continuous measurement in 20 m block (steady pace walks).
- ✓ Dedicated software package from CCRS.
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed.

✓ ***Hemispherical photography (HDP) (Nikon Coolpix 5000 and fish-eye)***

- ✓ Effective and ‘true LAI’, fAPAR, fCover, clump size index, canopy architecture
- ✓ Software: INRA Avignon software package CANEYE
- ✓ Discrete measurements on 20 m ESU points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed

✓ ***Licor LAI-2000***

- ✓ Measurement of effective LAI
- ✓ Discrete measurements on 20 m block points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Interesting comparisons possible with HDP and TRAC (I. Jonckheere, FEM, 2006)



VALERI *indirect method (HDP)*



CANEYE



➤ ***Indirect methods***

✓ ***Tracing radiation and Architecture of Canopies (TRAC – CCRS)***

- ✓ Gap size distribution, fAPAR, clumping index, effective LAI
- ✓ Continuous measurement in 20 m block (steady pace walks).
- ✓ Dedicated software package from CCRS.
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed.

✓ ***Hemispherical photography (HDP) (Nikon Coolpix 5000 and fish-eye)***

- ✓ Effective and ‘true LAI’, fAPAR, fCover, clump size index, canopy architecture
- ✓ Software: INRA Avignon software package CANEYE
- ✓ Discrete measurements on 20 m ESU points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Cloud free conditions needed

✓ ***Licor LAI-2000***

- ✓ Measurement of effective LAI
- ✓ Discrete measurements on 20 m block points A,B,C,D,E,F,G,H,O
- ✓ Time logging (Sun zenith angle)
- ✓ Interesting comparisons possible with HDP and TRAC (I. Jonckheere, FEM, 2006)



indirect method (LAI-2000)

LAI2000 file lay out and significance of measured and calculated variables

FILE	DATE	TIME	WHAT	WHERE	LAI	SEL	DIFN	MTA	SEM	SMP	
17	20-07-02	14:27:47	BEECH	ESU6	3.29	0.11	0.056	41	4	9	
ANGLES	7	23	38	53	68						Header
CNTCT#	2.414	2.607	2.531	1.839	1.018						
STDDEV	0.712	0.564	0.218	0.252	0.101						Statistics group
DISTS	1.008	1.087	1.27	1.662	2.67						
GAPS	0.088	0.059	0.041	0.048	0.067						
1	2	3	4	5	6	7	8				
A	1	14:37:26	137.5	107.1	89.83	71.36	24.43				
B	2	14:39:07	12.21	4.582	3.574	2.772	1.102				
B	3	14:39:19	32.69	10.29	4.873	3.274	1.519				
B	4	14:39:32	10.78	9.6	2.672	8.429	2.889				
B	5	14:39:53	7.318	8.982	5.75	5.39	1.499				Observations
B	6	14:40:10	37.14	18.24	4.112	2.886	2.162				
B	7	14:40:25	7.734	2.923	3.722	3.348	1.319				
B	8	14:40:37	3.253	4.106	2.149	2.549	1.445				
B	9	14:40:48	10.3	2.556	3.442	1.881	1.43				
B	10	14:41:01	18.16	6.968	3.551	2.892	1.736				
Header											
FILE:	file number					ANGLES:	Angles of the concentric circles for which the LAI measurement is performed				
DATE:	date dd/mm/jj					CNTCT#	Mean contact frequencies (the log of transmittance divided by path length)				
TIME:	time hh:mm:ss					STDDEV:	Standard deviation on the number of contacts				
WHAT:	Vegetation type					DISTS:	Path length (for full cover canopies = 1/cos(ANGLES))				
WHERE:	Elementary Sampling Unit Number					GAPS:	Gap fraction				
LAI:	Leaf Area Index					A:	Reference measurement outside the vegetation plot (or above)				
SEL:	Standard Deviation on LAI					B:	Measurement below the vegetation canopy				
DIFN:	Fraction of the sky visible beneath the canopy					Observations	Column 2:	Measurement number			
MTA:	Mean leaf Tilt Angle					Column 3:	time hh:mm:ss				
SEM:	Standard deviation on MTA					Column 4-8:	Observations (Signals of the 5 rings of the detector)				



VALERI indirect method (LAI-2000)

FILE	DATE	TIME	WHAT	WHERE	LAI	SEL	DIFN	MTA	SEM	SMP
17	20-07-02	14:27:47	BEECH	ESU6	3.29	0.11	0.056	41	4	9
ANGLES	7	23	38	53	68					
CNTCT#	2.414	2.607	2.531	1.839	1.018					
STDDEV	0.712	0.564	0.218	0.252	0.101					
DISTS	1.008	1.087	1.27	1.662	2.67					
GAPS	0.088	0.059	0.041	0.048	0.067					
A	1	14:37:26	137.5	107.1	89.83	71.36	24.43			
B	2	14:39:07	12.21	4.582	3.574	2.772	1.102			
B	3	14:39:19	32.69	10.29	4.873	3.274	1.519			
B	4	14:39:32	10.78	9.6	2.672	8.429	2.889			
B	5	14:39:53	7.318	8.982	5.75	5.39	1.499			
B	6	14:40:10	37.14	18.24	4.112	2.886	2.162			
B	7	14:40:25	7.734	2.923	3.722	3.348	1.319			
B	8	14:40:37	3.253	4.106	2.149	2.549	1.445			
B	9	14:40:48	10.3	2.556	3.442	1.881	1.43			
B	10	14:41:01	18.16	6.968	3.551	2.892	1.736			



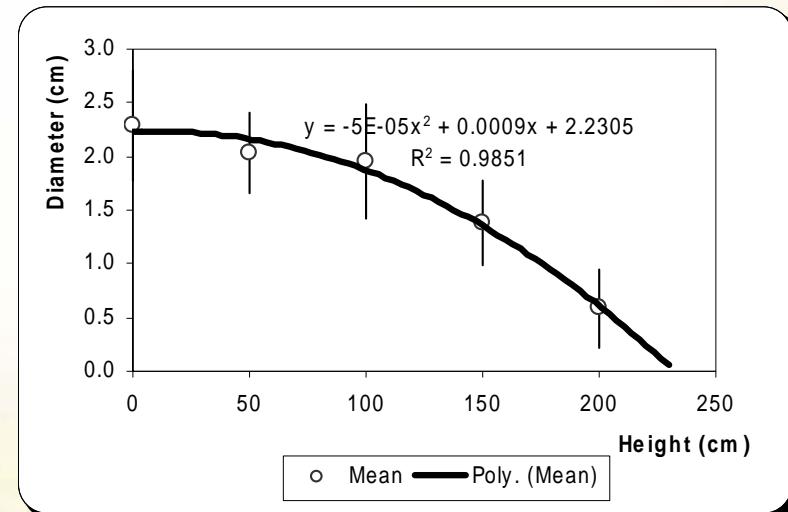
- **Direct method**
- **Field harvesting (FH)**

- ✓ Direct measurement of 'true' and effective LAI
- ✓ A square m² in the centre of an ESU
- ✓ Depends on harvesting permissions
- ✓ Comparison of reference 'true' and effective LAI with indirect methods



VALERI direct method (for LAI)

ESU:	40			
VEGETATION:	maize			
SAMPLED SURFACE	1 m ²			
NR OF SUBPLOTS	1			
PAI	3.6			
LAI	3.3			
GREEN L	BROWN L	STEMS	FRUITS	TOTAL
33299		2490		35789
cm ²		cm ²		cm ²



- The **VALERI** sampling strategy can be applied for heterogeneous patchy landscapes (Gilching case).
- The complete **VALERI** procedure has been applied at the Shandan and Gilching sites. Though both sites are very different at the landscape level, up-scaling to 1 km² pixels in both cases leads to **acceptable LAI validation fields**.
- Nevertheless, **not all landscapes are suitable** for the validation of bio-geophysical vegetation variables.
- The base site should be as flat as possible. Hence **(very) hilly terrain is excluded**.
- **Water bodies** are unwanted in the base site.





ESU = f (Panorama)

Thanks for your attention

Yellow river